



# COMMODORE SEMICONDUCTOR GROUP

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## CMOS

### 65CE02 MICROPROCESSOR

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#### DESCRIPTION

The Commodore 65CE02 is an enhanced version of the popular 8-bit 6502, designed with entirely new internal architecture and manufactured in 2-micron, double-level-metal, CMOS technology for high speed and low power consumption. The 65CE02 is code (\*) and pin compatible with existing 6502/65C02's.

The instruction set has been streamlined, removing most 'dead' cycles which occurred due to page boundaries and micro-code pipelines, allowing existing code to run up to 25% faster. Additional instructions and addressing modes allow even greater program efficiency. Add to this operational speeds of up to 10MHz (100ns instruction cycles) and the 65CE02 is capable of a 350% decrease in program execution time compared to a standard 4MHz 6502.

The 65CE02 provides the system designer with a high performance, low power microprocessor, while retaining downward compatibility with the existing family of microprocessor support devices.

(\*) Application programs should be analyzed to see if they contain timing loops or previously undefined opcodes.

#### FEATURES

- CMOS technology for low power consumption
- 0 - 10 MHz operating speeds
- Single +5V supply required
- Eight-bit parallel processing
- Code compatible with existing 6502/65C02
- Execution times independent of page boundary crossings
- Executes existing 6502/65C02 code in up to 25% fewer cycles
- 16-bit stack pointer with two modes of operation
  - full 16-bit pointer
  - page programmable 8-bit pointer
- Base page register allows relocation of 'zero' page
- Three index registers: X, Y, Z
- Maskable & non-maskable interrupt capability
- 64K byte memory address space
- Direct memory access (DMA) capability
- 'Ready' input
- On-chip clock generates  $\phi_1/\phi_2$
- Enhanced instruction set
  - 24 new instructions, for a total of 92
  - 46 new op codes, for a total of 256
  - Three new addressing modes
- Cross-assembler and low cost hardware emulator available

FIGURE 1  
PIN CONFIGURATION

$V_{SS}$	1	40	$\overline{RES}$
RDY	2	39	$\phi_2$
$\phi_1$	3	38	$\overline{SO}$
$\overline{IRQ}$	4	37	$\phi_0$
N.C.	5	36	N.C.
$\overline{NMI}$	6	35	N.C.
SYNC	7	34	R/W
$V_{CC}$	8	33	D <sub>0</sub>
A <sub>0</sub>	9	32	D <sub>1</sub>
A <sub>1</sub>	10	31	D <sub>2</sub>
A <sub>2</sub>	11	30	D <sub>3</sub>
A <sub>3</sub>	12	29	D <sub>4</sub>
A <sub>4</sub>	13	28	D <sub>5</sub>
A <sub>5</sub>	14	27	D <sub>6</sub>
A <sub>6</sub>	15	26	D <sub>7</sub>
A <sub>7</sub>	16	25	A <sub>15</sub>
A <sub>8</sub>	17	24	A <sub>14</sub>
A <sub>9</sub>	18	23	A <sub>13</sub>
A <sub>10</sub>	19	22	A <sub>12</sub>
A <sub>11</sub>	20	21	$V_{SS}$

PRELIMINARY

## SUMMARY OF 65CE02 ENHANCEMENTS

The 65CE02, upon reset, configures itself like any present CMOS 6502 processor, with the exception that many instructions require fewer cycles. This results in programs that execute in less time than older versions, even at the same clock frequency.

The stack pointer has been expanded to 16 bits, but can be used in two different ways. It can be used as a full 16-bit (word) stack pointer, or as an 8-bit (byte) pointer whose stack page is programmable. On reset, the byte mode is selected with page 01 set as the stack page, maintaining 6502 and 65C02 compatibility.

The zero page is also programmable via a new register, the "B" or "Base Page" register. On reset, this register is cleared, thus giving a true "zero" page. The user can then re-define any page in memory as the "zero" page.

A third index register, "Z", has been added to increase flexibility in data manipulation. This register is cleared on reset, providing STZ instruction compatibility with the 65C02.

All branching instructions have been expanded to include a 'word relative' addressing mode which allows branching anywhere within the 64K memory space. A new word relative branch to subroutine aids the programmer in creating re-locatable code modules, resulting in increased software flexibility.

Also included is an addressing mode which facilitates parameter passing to subroutines. Parameters and/or pointers to data arrays can be passed to a subroutine via the stack, and a special return instruction will 'fix' the stack pointer when the subroutine is finished.

The BIT (IMMEDIATE) test will set the N and V flags with valid states, which was not the case with earlier 65C02s. The BCD arithmetic instructions modify the N, Z, V, and C flags correctly, as was not the case in the 6502.

The following is a list of opcodes that have been added to the 210 previously defined MOS, Rockwell, and GTE opcodes.

### 1. Branches and Jumps

BPL	label	word-relative
BMI	label	word-relative
BRU	label	word-relative (BRA)
BVC	label	word-relative
BVS	label	word-relative
BCC	label	word-relative
BCS	label	word-relative
BNE	label	word-relative
BEQ	label	word-relative
BSR	label	Branch to SubRoutine (word relative)
JSR	(ABS)	Jump to SubRoutine absolute indirect
JSR	(ABS, X)	Jump to SubRoutine absolute indirect, X
RTN	#	ReTurN from subroutine and adjust stack pointer.

### 2. Arithmetic Operations

NEG	A	NEGate (or 2's complement) accumulator.
ASR	A	Arithmetic Shift Right; accumulator or
ASR	BP	memory
ASR	BP, X	

INW	BP	INcrement Word
DEW	BP	DEcrement Word
INZ		INcrement Z register
DEZ		DEcrement Z register
ASW	ABS	Arithmetic Shift left Word
ROW	ABS	ROtate left Word
ORA	(BP), Z	formerly (ZP) non-indexed that are now indexed by Z register
AND	(BP), Z	
EOR	(BP), Z	
ADC	(BP), Z	
CMP	(BP), Z	
SBC	(BP), Z	
CPZ	IMM	ComPare Z register with memory immediate,
CPZ	BP	base page, and
CPZ	ABS	absolute.

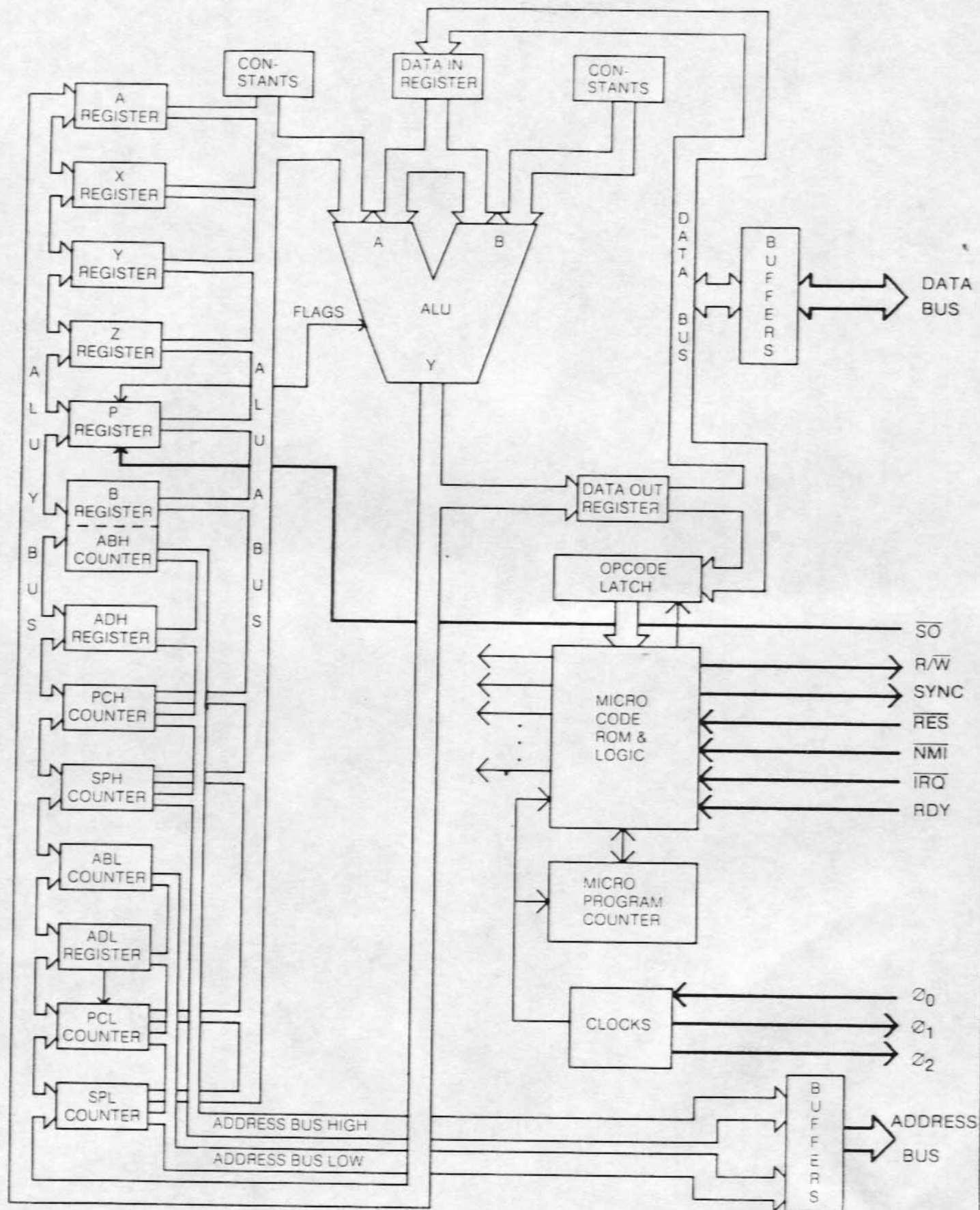
### 3. Loads, Stores, Pushes, Pulls and Transfers

LDA	(BP), Z	formerly (ZP)
LDZ	IMM	LoaD Z register immediate,
LDZ	ABS	absolute
LDZ	ABS, X	absolute, X.
LDA	(d, SP), Y	LoaD Accum via stack vector indexed by Y
STA	(d, SP), Y	and Store
STX	ABS, Y	STore X Absolute, Y
STY	ABS, X	STore Y Absolute, X
STZ	BP	STore Z register (formerly store zero)
STZ	ABS	
STZ	BP, X	
STZ	ABS, X	
STA	(BP), Z	formerly (ZP)
CLE		CLear stack Extend disable bit
SEE		SEt stack Extend disable bit
PHW	IMM	Push Data Immediate (Word)
PHW	ABS	Push Data Absolute (Word)
PHZ		Push Z register onto stack
PLZ		PuLl Z register from stack
TAZ		Transfer Accumulator to Z register
TZA		Transfer Z register to Accumulator
TAB		Transfer Accumulator to Base page register
TBA		Transfer Base page register to Accumulator
TSY		Transfer Stack pointer high byte to Y register
TYS		Transfer Y register to Stack pointer high byte

### 4. Special Instructions

AUG		AUGment Instruction (4-byte NOP, reserved for future expansion)
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FIGURE 2  
65CE02 FUNCTIONAL BLOCK DIAGRAM





## FUNCTIONAL DESCRIPTION

Figure 2 shows the block diagram of the 65CE02 CPU's internal architecture. This diagram supports the following description of the device's major elements.

### Clock

The clock circuitry accepts the external  $\phi_0$  clock rate and from it generates all required internal clock control signals. It provides the external  $\phi_1$  and  $\phi_2$  signals from which all inputs and outputs are referenced.

### Micro Program Counter, Micro Code ROM and Logic PLA

This block controls and implements the opcode sequences.

### Arithmetic and Logic Unit (ALU)

All arithmetic and logic operations are executed in the ALU. The ALU has no internal memory and all operational outputs are directed to the internal register/counter specified by the opcode.

### Accumulator

The accumulator is a general purpose 8-bit computational register used for arithmetic and Boolean functions. It can not be used for indexing.

### Index Registers (X, Y, Z)

There are three 8-bit index registers which may be incremented, decremented, compared or used to provide an index value to generate an effective address. The newly added Z register is cleared upon RESET allowing code compatibility with the 65C02.

When executing an instruction which specifies indexed addressing, the CPU fetches the OP code and the base address, and modifies the address by adding the index register value to it prior to performing the desired operation. Pre- or post-indexing of indirect addresses is possible (see addressing modes).

### Base Page Register (B)

The Base Page register contains the value of the high order address byte used in the base page (formerly 'zero page') addressing modes. This register is programmable, via the TAB instruction, allowing any page in memory to function as the base page. On reset, the B register is cleared, initially providing a true "zero page".

### Processor Status Register (P)

The 8-bit status register contains the values of the 8 status flags. Some flags are controlled by the program, while others are controlled by both the program and the ALU. One additional flag is present which enables extended (16-bit) stack pointer operation. The flags can be tested by a number of conditional branch instructions.

### Address Counters (ABL and ABH) and Address Registers (ADL and ADH)

These registers are used to provide the 16-bits of addressing information for memory and I/O exchanges. A unique design feature allows ADL and ADH to store indirect address vectors while ABL and ABH function as counters, thus relieving the ALU from internal address fetches and increasing throughput.

### Stack Pointer Counter (SPH and SPL)

The stack pointer is a 16 bit register that can operate in two modes. It can be programmed to be either an 8-bit page programmable pointer, or a full 16-bit pointer. The processor status E bit selects the 8-bit mode when set, and selects the 16-bit mode when reset.

Upon reset, the 65CE02 will be configured in the 8-bit page-programmable mode, with the stack page set to 01. This maintains compatibility with earlier 6502 products. The programmer can quickly change the default stack page by loading the Y register with the desired page and transferring its contents to the stack pointer high byte, using the TYS opcode. The 8-bit stack pointer can be set by loading the X register with the desired value, and transferring its contents to the stack pointer low byte, using the TXS opcode.

To select the 16-bit stack pointer mode, the user must execute a CLE (for CLear Extend disable) opcode. Setting the 16-bit pointer is done by loading the X and Y registers with the desired stack pointer low and high bytes, respectively, and then transferring their contents to the stack pointer using TXS and TYS. To return to 8-bit page mode, simply execute a SEE (SEt Extend disable) opcode.

### CAUTION

When using interrupts, and BOTH stack pointer bytes are to be changed, do NOT put any code between the TXS and TYS opcodes. Taking this precaution will prevent any interrupts from occurring between the setting of the two stack pointer bytes, thus preventing the writing of stack data to an incorrect area.

### Program Counter (PCL and PCH)

This 16-bit up counter determines the area of memory from which program information will be fetched. The user can modify the contents with jumps, branches, subroutine calls, or returns. It is set initially, and by interrupts, from vectors at memory addresses FFFA through FFFF (hex). See IRQ, NMI and RESET below.

## SIGNAL DESCRIPTIONS

### Clock Signals

The 65CE02 requires an external, TTL-level  $\phi_0$  clock. Two full level clocks ( $\phi_1$  and  $\phi_2$ ) are generated by the 65CE02:  $\phi_2$  in phase with  $\phi_0$ , and  $\phi_1$  180 degrees out of phase with  $\phi_0$ . The input clock may be stopped in either phase to place the CPU into standby mode.

For non-critical timing applications, a simple RC or crystal network may be connected between  $\phi_0$  (in) and  $\phi_1$  (out).

### Address Bus

A<sub>0</sub>-A<sub>15</sub> forms a 16-bit address bus for memory and I/O exchanges on the data bus. The output of each address line is TTL compatible, capable of driving two standard TTL loads and 55pF.



## Data Bus

D<sub>0</sub>-D<sub>7</sub> form an 8-bit bidirectional data bus for data exchanges to and from the 65CE02 and peripheral devices. The output buffers are capable of driving two standard TTL loads and 55pF. This bus is tristated during 'read' operations, during  $\phi_2$  low time, and throughout any cycle where RDY is pulled 'low' prior to  $\phi_2$  rising.

## Interrupt Request ( $\overline{\text{IRQ}}$ )

This active-low input requests that an interrupt sequence begin within the microprocessor. If the interrupt mask flag (I) in the status register is zero, an interrupt sequence will begin with the first SYNC after a multiple-cycle opcode. The program counter and processor status register are then stored on the stack and the interrupt mask flag is set so that no further  $\overline{\text{IRQ}}$ 's may occur. The program counter low byte (PCL) is then loaded from address FFFE, and the high byte (PCH) from FFFF. Program execution will continue from the vector located at these addresses.

## Non-Maskable Interrupt ( $\overline{\text{NMI}}$ )

The NMI input cannot be masked by the processor status register I flag and will cause an interrupt after receiving a high to low transition. This interrupt sequence will begin with the first SYNC after a multiple-cycle opcode. The two program counter bytes, PCH and PCL, and the processor status register P, are pushed onto the stack. The program counter bytes PCL and PCH are then loaded from memory addresses FFFA and FFFB, respectively. Program execution will then continue from the vector located at these addresses.

### INTERRUPT NOTES

1. Since  $\overline{\text{NMI}}$  is non-maskable, another  $\overline{\text{NMI}}$  can occur before the first is finished. Care should be taken to avoid this.
2. The RDY signal must be 'high' to insure  $\overline{\text{IRQ}}$  is recognized. The  $\overline{\text{NMI}}$  input is edge activated and the 65CE02 will remember an NMI event, even if it is prevented from acting upon it by deasserting RDY.
3. A 3K ohm external pull-up resistor should be used for proper wire-OR operation.

## Ready (RDY)

This input signal allows the user to single-cycle the microprocessor on all cycles including write cycles. A negative transition during or coincident with  $\phi_1$  will halt the microprocessor with the output address lines reflecting the current address. This condition will remain throughout subsequent  $\phi_2$  cycles in which the RDY signal is held 'low'. The RDY feature allows microprocessor interfacing with low speed memory as well as Direct Memory Access (DMA).

## Read/Write (R/ $\overline{\text{W}}$ )

The R/ $\overline{\text{W}}$  output signal remains in the 'high' state while the 65CE02 is reading data from memory or peripherals on the 8-bit data bus. When 'low', valid output data is available on the data bus.

## Set Overflow ( $\overline{\text{SO}}$ )

A negative transition on this input sets the overflow bit (V) in the processor status register. The signal is sampled on the rising edge of  $\phi_2$ .

## Reset ( $\overline{\text{RES}}$ )

The  $\overline{\text{RES}}$  input instantly resets the 65CE02.  $\overline{\text{RES}}$  should be held 'low' for at least 2 clock cycles after V<sub>DD</sub> reaches operating voltage during power-up. Likewise, after the system has been operating, a low on this line will cease microprocessing activity. A positive transition on this pin begins an initialization sequence lasting six clock cycles.

The stack pointer is set to "byte" mode and the stack page is set to page 01. The B and Z registers are cleared and the processor status bits E and I will be set. The program counter is loaded with the restart vector from locations FFFC (low byte) and FFFD (high byte). This is the startup location for program control. During normal operation,  $\overline{\text{RES}}$  should be held 'high'.

## Synchronize (SYNC)

The SYNC output signal identifies those cycles in which the microprocessor is fetching OP CODE data. The SYNC line goes 'high' during  $\phi_1$  of an OP CODE fetch and stays 'high' for the remainder of that cycle. If the RDY line is pulled 'low' during the  $\phi_1$  pulse in which SYNC went 'high', the processor will stop and remain in its current state until the RDY line goes 'high'. In this manner, the SYNC signal can be used to control RDY for single instruction execution.

## ADDRESSING MODES

The 65CE02 has 18 addressing modes (3 more than the 65C02, and 5 more than the 6502). The bracketed expression following the title of the mode is used later to identify the addressing mode in the Instruction Set Op Code Matrix and Summary tables.

### Immediate [IMM]

In immediate addressing the second byte of the instruction contains the operand, with no further memory addressing required. (PHW - Push Word - requires a third byte).

### Absolute [ABS]

In absolute addressing, the second byte of the instruction specifies the eight low order bits of the effective address while the third byte specifies the eight high order bits. Thus the absolute addressing mode allows access to the entire 64K bytes of addressable memory.

### Base Page [BP]

The base page mode allows for shorter code and execution time by using the contents of the base page register as the high order address byte. This differs from the previous Zero Page addressing mode in that the 'zero page' may now be relocated, thus making memory mapping more flexible and coding more efficient.

### Accumulator [ACCUM]

This form of addressing is represented with a one-byte instruction, implying an operation on the accumulator.

### **Implied [IMPL]**

In the implied addressing mode, the address containing the operand is implicitly stated in the operation code of the instruction.

### **Base Page Indexed [BP, X or BP, Y] (note 1)**

This form of base page addressing calculates the effective low order address byte by adding the second instruction byte to the contents of the indexing register (X or Y). The high order byte is specified by the contents of the base page register. Additionally, due to the nature of "base page" addressing, no carry is added to the high order byte and page boundary crossing does not occur.

### **Absolute Indexed [ABS, X or ABS, Y]**

This mode forms the effective address by adding the contents of X (or Y) to the address contained in the second and third bytes of the instruction. The index register contains the index or count value and the instruction specifies the base address.

### **Indexed Indirect [(BP, X)] (note 1)**

In indexed indirect addressing, the second byte of the instruction is added to the contents of the X index register, discarding the carry. The result of this addition points to a memory location in Base Page whose contents are the low order eight bits of the effective address. The next memory location in Base Page contains the high order eight bits of the effective address.

### **Indirect Indexed [(BP), Y or (BP), Z] (notes 1, 2)**

In indirect indexed addressing, the second byte of the instruction points to a memory location in Base Page. The contents of this location and the Y (or Z) index register are added, the result being the low order eight bits of the effective address. The carry from this addition is added to the contents of the next Base Page memory location, providing the high order eight bits of the effective address.

### **Stack Vector Indirect Indexed [(D, SP), Y] (note 3)**

This new mode is similar to indirect indexed addressing. The Stack replaces the Base Page and the second instruction byte specifies the displacement from the current stack pointer location rather than the location within Base Page.

The contents of this displaced stack location are added to the contents of the Y index register, the result being the low order eight bits of the effective address. The carry from this addition is added to the contents of the next (D+1) stack location, the result being the high order eight bits of the effective address.

### **Relative - Byte [REL]**

Relative addressing is used only with branch instructions and establishes the destination for the branch. The second byte of the instruction is the "offset", whose range is -128 to 127 bytes, and is added to the address of the instruction following the branch.

### **Relative - Word [WREL] (note 3)**

Similar to above but uses the second and third bytes as the "offset". The range of the offset is -32768 to +32767 bytes relative to the address of the third instruction byte (not the next instruction).

### **Absolute Indirect [(ABS)]**

In the ABS mode the second and third bytes of the instruction respectively contain the lower and upper eight bits of a memory location. The content of this memory location is the low order byte of the effective address. The next memory location contains the high order byte of the effective address.

### **Base Page Relative [BP REL] (notes 1, 4)**

This mode is used only with the bit-test branch instructions (BBS and BCC). The second byte of the instruction specifies the low order byte of Base Page memory to be tested. The third byte of the instruction is the offset, whose range is -128 to 127 bytes, referenced to the location of the next instruction.

### **Indexed Absolute Indirect [(ABS,X)] (note 4)**

In this addressing mode the contents of the second and third instruction bytes are added to the X register. The sixteen bit result is a memory address containing the effective low order address byte. The next memory location contains the high order byte of the effective address.

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note 1 - referenced to base page, not necessarily zero page.

2 - (BP), Z is a new addressing mode allowing indexing from the new Z register; it can also be used as the 65C02 uses (IND) by setting base page = zero page, and the contents of Z to \$00 (default condition after RESET).

3 - new addressing mode not available on 65C02 or 6502.

4 - not available on 6502.



# 65CE02 OPCODE MATRIX

		LSD																	
		0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F		
MSD	0	BRK IMPLIED 2.7	ORA (BP, X) 2.5	CLE IMPLIED 1.2	SEE IMPLIED 1.2	TSB BP 2.4	ORA BP 2.3	ASL BP 2.4	RMB0 BP 2.4	PHP IMPLIED 1.3	ORA IMM 2.2	ASL ACCUM 1.1	TSY IMPLIED 1.1	TSB ABS 3.5	ORA ABS 3.4	ASL ABS 3.5	BBR0 BP 3.4	0	
	1	BPL REL 2.2	ORA (BP, Y) 2.5	ORA (BP, Z) 2.5	BPL W REL 3.3	TRB BP 2.4	ORA BP, X 2.3	ASL BP, X 2.4	RMB1 BP 2.4	CLC IMPLIED 1.1	ORA ABS, Y 3.4	INC ACCUM 1.1	INZ IMPLIED 1.1	TRB ABS 3.5	ORA ABS, X 3.4	ASL ABS, X 3.5	BBR1 BP 3.4	1	
	2	JSR ABS 3.5	AND (BP, X) 2.5	JSR (ABS) 3.7	JSR (ABS, X) 3.7	BIT BP 2.4	AND BP 2.3	ROL BP 2.4	RMB2 BP 2.4	PLP IMPLIED 1.3	AND IMM 2.2	ROL ACCUM 1.1	TYS IMPLIED 1.1	BIT ABS 3.5	AND ABS 3.4	ROL ABS 3.5	BBR2 BP 3.4	2	
	3	BMI REL 2.2	AND (BP, Y) 2.5	AND (BP, Z) 2.5	BMI W REL 3.3	BIT BP, X 2.4	AND BP, X 2.3	ROL BP, X 2.4	RMB3 BP 2.4	SEC IMPLIED 1.1	AND ABS, Y 3.4	DEC ACCUM 1.1	DEZ IMPLIED 1.1	BIT ABS, X 3.5	AND ABS, X 3.4	ROL ABS, X 3.5	BBR3 BP 3.4	3	
	4	RTI IMPLIED 1.5	EOR (BP, X) 2.5	NEG ACCUM 1.2	ASR ACCUM 1.2	ASR BP 2.4	EOR BP 2.3	LSR BP 2.4	RMB4 BP 2.4	PHA IMPLIED 1.3	EOR IMM 2.2	LSR ACCUM 1.1	TAZ IMPLIED 1.1	JMP ABS 3.3	EOR ABS 3.4	LSR ABS 3.5	BBR4 BP 3.4	4	
	5	BVC REL 2.2	EOR (BP, Y) 2.5	EOR (BP, Z) 2.5	BVC W REL 3.3	ASR BP, X 2.4	EOR BP, X 2.3	LSR BP, X 2.4	RMB5 BP 2.4	CLI IMPLIED 1.1	EOR ABS, Y 3.4	PHY IMPLIED 1.3	TAB IMPLIED 1.1	AUG IMPLIED 4.4	EOR ABS, X 3.4	LSR ABS, X 3.5	BBR5 BP 3.4	5	
	6	RTS IMPLIED 1.4	ADC (BP, X) 2.5	RTN IMPLIED 2.7	BSR W REL 3.5	STZ BP 2.3	ADC BP 2.3	ROR BP 2.4	RMB6 BP 2.4	PLA IMPLIED 1.3	ADC IMM 2.2	ROR ACCUM 1.1	TZA IMPLIED 1.1	JMP (ABS) 3.5	ADC ABS 3.4	ROR ABS 3.5	BBR6 BP 3.4	6	
	7	BVS REL 2.2	ADC (BP, Y) 2.5	ADC (BP, Z) 2.5	BVS W REL 3.3	STZ BP, X 2.3	ADC BP, X 2.3	ROR BP, X 2.4	RMB7 BP 2.4	SEI IMPLIED 1.2	ADC ABS, Y 3.4	PLY IMPLIED 1.3	TBA IMPLIED 1.1	JMP (ABS, X) 3.5	ADC ABS, X 3.4	ROR ABS, X 3.5	BBR7 BP 3.4	7	MSD
	8	BRU REL 2.2	STA (BP, X) 2.5	STA (d.SP, Y) 2.6	BRU W REL 3.3	STY BP 2.3	STA BP 2.3	STX BP 2.3	SMB0 BP 2.4	DEY IMPLIED 1.1	BIT IMM 2.2	TXA IMPLIED 1.1	STY ABS, X 3.4	STY ABS 3.4	STA ABS 3.4	STX ABS 3.4	BB50 BP 3.4	8	
	9	BCC REL 2.2	STA (BP, Y) 2.5	STA (BP, Z) 2.5	BCC W REL 3.3	STY BP, X 2.3	STA BP, X 2.3	STX BP, Y 2.3	SMB1 BP 2.4	TYA IMPLIED 1.1	STA ABS, Y 3.4	TXS IMPLIED 1.1	STX ABS, Y 3.4	STZ ABS 3.4	STA ABS, X 3.4	STZ ABS, X 3.4	BB51 BP 3.4	9	
	A	LDY IMM 2.2	LDA (BP, X) 2.5	LDX IMM 2.2	LDZ IMM 2.2	LDY BP 2.3	LDA BP 2.3	LDX BP 2.3	SMB2 BP 2.4	TAY IMPLIED 1.1	LDA IMM 2.2	TAX IMPLIED 1.1	LDZ ABS 3.4	LDY ABS 3.4	LDA ABS 3.4	LDX ABS 3.4	BB52 BP 3.4	A	
	B	BLS REL 2.2	LDA (BP, Y) 2.5	LDA (BP, Z) 2.5	BCS W REL 3.3	LDY BP, X 2.3	LDA BP, X 2.3	LDX BP, Y 2.3	SMB3 BP 2.4	CLV IMPLIED 1.1	LDA ABS, Y 3.4	TSX IMPLIED 1.1	LDZ ABS, X 3.4	LDY ABS, X 3.4	LDA ABS, X 3.4	LDX ABS, Y 3.4	BB53 BP 3.4	B	
	C	CPY IMM 2.2	CMP (BP, X) 2.5	CPZ IMM 2.2	DEW BP 2.6	CPY BP 2.3	CMP BP 2.3	DEC BP 2.4	SMB4 BP 2.4	INY IMPLIED 1.1	CMP IMM 2.2	DEX IMPLIED 1.1	ASW ABS 3.7	CPY ABS 3.4	CMP ABS 3.4	DEC ABS 3.5	BB54 BP 3.4	C	
	D	BNE REL 2.2	CMP (BP, Y) 2.5	CMP (BP, Z) 2.5	BNE W REL 3.3	CPZ BP 2.3	CMP BP, X 2.3	DEC BP, X 2.4	SMB5 BP 2.4	CLD IMPLIED 1.1	CMP ABS, Y 3.4	PHX IMPLIED 1.3	PHZ IMPLIED 1.3	CPZ ABS 3.4	CMP ABS, X 3.4	DEC ABS, X 3.5	BB55 BP 3.4	D	
	E	CPX IMM 2.2	SBC (BP, X) 2.5	LDA (d.SP, Y) 2.6	INW BP 2.6	CPX BP 2.3	SBC BP 2.3	INC BP 2.4	SMB6 BP 2.4	INX IMPLIED 1.1	SBC IMM 2.2	NOP IMPLIED 1.1	ROW ABS 2.6	CPX ABS 3.4	SBC ABS 3.4	INC ABS 3.5	BB56 BP 3.4	E	
	F	BEQ REL 2.2	SBC (BP, Y) 2.5	SBC (BP, Z) 2.5	BEQ W REL 3.3	PHW IMM W 3.5	SBC BP, X 2.3	INC BP, X 2.4	SMB7 BP 2.4	SED IMPLIED 1.1	SBC ABS, Y 3.4	PLX IMPLIED 1.3	PLZ IMPLIED 1.3	PHW ABS W 3.7	SBC ABS, X 3.4	INC ABS, X 3.5	BB57 BP 3.4	F	
		0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F		
		LSD																	



NEW  
OPCODE

0  
BRK  
IMPLIED  
2.7

- OPCODE
- ADDRESSING MODE
- Instruction Bytes, Machine Cycles

Note that the number of machine cycles for every instruction remains fixed, regardless of decimal mode and page boundaries.



## DC CHARACTERISTICS

### Absolute Maximum Ratings

Stresses above those listed may cause permanent damage to the circuit. Functional operation of the device at these or any conditions other than those indicated in the Operating Conditions of this specification is not implied. Exposure to the maximum ratings for extended periods may adversely affect device reliability.

Characteristic	Min	Max	Units
Ambient temperature under bias	-25	+125	deg C
Storage temperature	-65	+125	deg C
Applied supply voltage	-0.5	+7.0	volts
Applied output voltage	-0.5	+5.5	volts
Applied input voltage	-2.0	+7.0	volts

### Operating Conditions

All electrical characteristics are specified over the entire range of the operating conditions unless otherwise noted. All voltages are referenced to  $V_{SS} = 0.0$  V

Condition	Min	Max	Units
Supply voltage ( $V_{DD}$ )	4.5	5.5	volts
Free air temperature	0	70	deg C

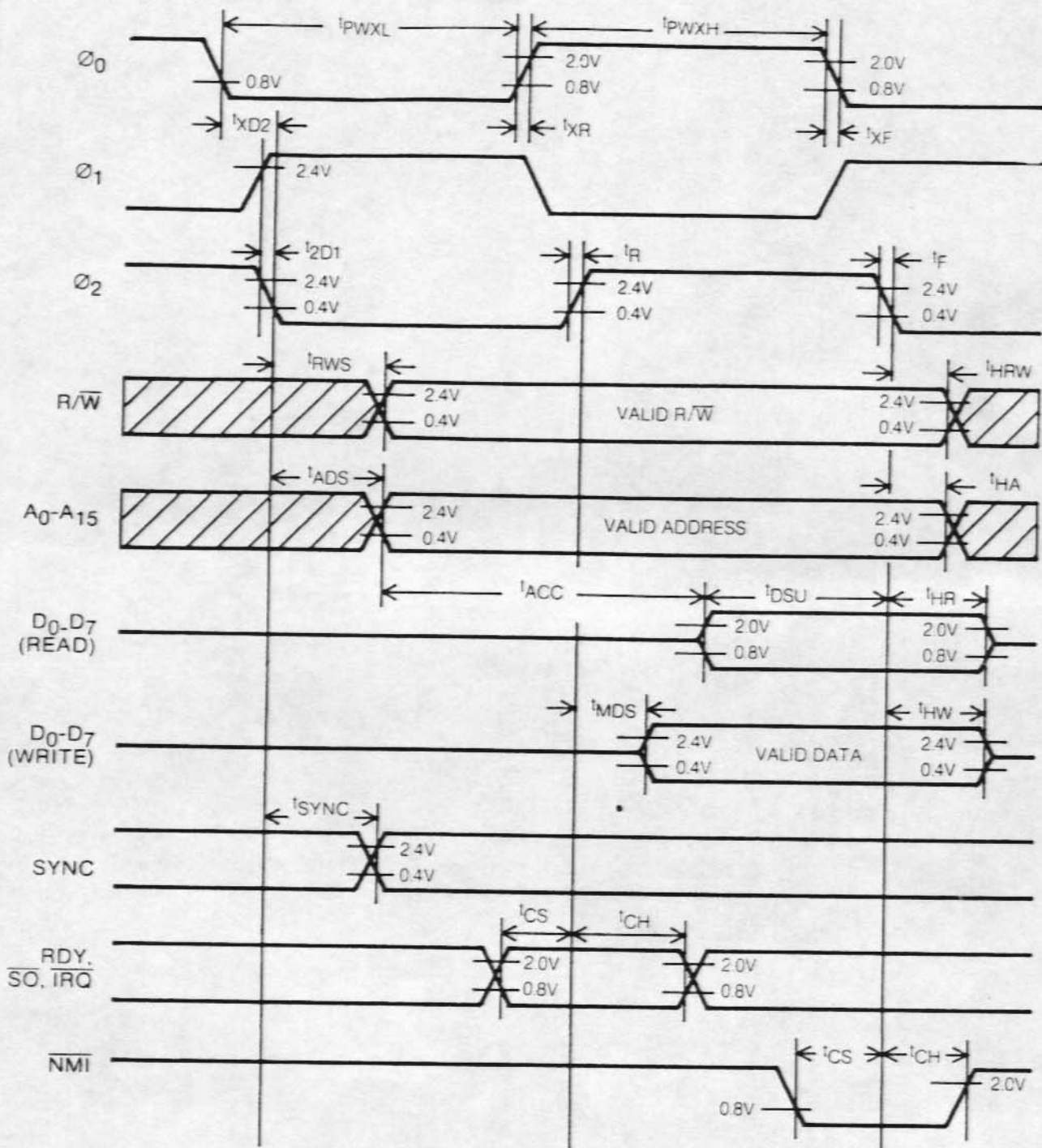
### Interface Characteristics

Characteristic	Symbol	Min	Max	Units	Conditions
Input High Level	$V_{IH}$	2.0	$V_{DD}$	Volts	$0.0V < V_{IN} < V_{DD}$
Input Low Level	$V_{IL}$	-0.5	0.8	Volts	
Input Leakage	$I_{IN}$	-10	10	$\mu$ Amps	
Output High Level	$V_{OH}$	2.4	-	Volts	$I_{load} = -200\mu A$
Output Low Level	$V_{OL}$	-	0.4	Volts	
Supply Current	$I_{DD}$	-	10	$\mu$ Amps	standby
		-	3.5	mA/MHz	
Input Capacitance	$C_{IN}$	-	10	pF	$V_{IN}=0V, f=4MHz$
Output Capacitance	$C_{OUT}$	-	10	pF	

### 65CE02 TIMING SPECIFICATION

Parameter	Symbol	2 MHz		4 MHz		6 MHz		8 MHz		10 MHz	
		MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX
Cycle time	$t_{CYC}$	500		250		167		125		100	
Ext Clk Width Low	$t_{PWL}$	230		115		75		55		45	
Ext Clk Width High	$t_{PWH}$	230		115		75		55		45	
Ext low to $\phi_2$ low	$t_{XD2}$	5	40	5	30	5	30	5	30	5	25
$\phi_2$ low to $\phi_1$ high	$t_{2D1}$	-20	20	-15	15	-10	10	-10	10	-10	10
$\phi_2$ Clk Rise, Fall	$t_R, t_F$		20		15		10		10		10
Ext Signal Rise, Fall	$t_{XR}, t_{XF}$		20		15		10		10		10
Read/Write Setup	$t_{RWS}$		50		40		35		30		25
Read/Write Hold	$t_{HRW}$	15		15		10		10		5	15
Address Setup	$t_{ADS}$		50		40		35		30		25
Address Hold	$t_{HA}$	15		15		10		10		5	15
Read Access	$t_{ACC}$	390		170		102		70		55	
Read Data Setup	$t_{DSU}$	60		40		30		25		20	
Read Data Hold	$t_{HR}$	10		10		10		10		10	
Write Data Delay	$t_{MDS}$		100		50		40		35		30
Write Data Hold	$t_{HW}$	15		15		10		10		5	15
SYNC Delay	$t_{SYNC}$		50		40		35		30		25
RDY SO IRQ NMI Setup	$t_{CS}$	50		30		30		25		20	
RDY SO IRQ NMI Hold	$t_{CH}$	30		25		25		20		20	

# 65CE02 TIMING DIAGRAM



# 65CE02 INSTRUCTION SET SUMMARY

INSTRUCTIONS		ADDRESSING MODES									
Mnemonic	Operation	IMM	ABS	BP	ACCUM	IMPL	(BP, X)	(BP), Y	(BP), Z	(D, SP), Y	
		OP N #	OP N #	OP N #	OP N #	OP N #	OP N #	OP N #	OP N #	OP N #	
ADC	A ← M ← C ← A	69 2 2	6D 4 3	65 3 2				61 5 2	71 5 2	72 5 2	
AND	A ← A and M ← A	29 2 2	2D 4 3	25 3 2				21 5 2	31 5 2	32 5 2	
ASL	C ← /7...0/ ← 0		0E 5 3	06 4 2	0A 1 1						
ASR	M7 ← /7...0/ ← C			44 4 2	43 2 1						
ASW	C ← /15...0/ ← 0		CB 7 3								
AUG	No Operation										
BIT	A and M	89 2 2	2C 5 3	24 4 2		5C 4 4					
BBR	Branch on Bit Reset										
BBS	Branch on Bit Set										
BCC	Branch on C = 0										
BCS	Branch on C = 1										
BEQ	Branch on Z = 1										
BMI	Branch on N = 1										
BNE	Branch on Z = 0										
BPL	Branch on N = 0										
BRK	BReAK					00 7 2					
BRU (BRA)	BRanch Unconditional										
BSR	Branch to SubRoutine										
BVC	Branch on V = 0										
BVS	Branch on V = 1										
CLC	0 ← C					18 1 1					
CLD	0 ← D					D8 1 1					
CLE	0 ← E					02 2 1					
CLI	0 ← I					58 2 1					
CLV	0 ← V					B8 1 1					
CMP	A ← M	C9 2 2	CD 4 3	C5 3 2			C1 5 2	D1 5 2	D2 5 2		
CPX	X ← M	E0 2 2	EC 4 3	E4 3 2							
CPY	Y ← M	C0 2 2	CC 4 3	C4 3 2							
CPZ	Z ← M	C2 2 2	DC 4 3	D4 3 2							
DEC	M ← 1 ← M		CE 5 3	C6 4 2	3A 1 1						
DEW	Mw ← 1 ← Mw			C3 6 2							
DEX	X ← 1 ← X					CA 1 1					
DEY	Y ← 1 ← Y					BA 1 1					
DEZ	Z ← 1 ← Z					3B 1 1					
EOR	A ← A exclu or. M ← A	49 2 2	4D 4 3	45 3 2			41 5 2	51 5 2	52 5 2		
INC	M ← 1 ← M		EE 5 3	E6 4 2	1A 1 1						
INW	Mw ← 1 ← Mw			E3 6 2							
INX	X ← 1 ← X					E8 1 1					
INY	Y ← 1 ← Y					C8 1 1					
INZ	Z ← 1 ← Z					1B 1 1					
JMP	JuMP to new location		4C 3 3								
JSR	Jump to SubRoutine		20 5 3								
LDA	M ← A	A9 2 2	AD 4 3	A5 3 2			A1 5 2	B1 5 2	B2 5 2	E2 6 2	
LDX	M ← X	A2 2 2	AE 4 3	A6 3 2							
LDY	M ← Y	A0 2 2	AC 4 3	A4 3 2							
LDZ	M ← Z	A3 2 2	AB 4 3								
LSR	0 ← /7...0/ ← C		4E 5 3	46 4 2	4A 1 1						
NEG	1 ← A ← A				42 2 1						
NOP	No Operation					EA 1 1					
ORA	A ← A or M ← A	09 2 2	0D 4 3	05 3 2			01 5 2	11 5 2	12 5 2		
PHA	A ← Ms.S-1 ← S					48 3 1					
PHP	P ← Ms.S-1 ← S					08 3 1					
PHW	Mw ← Ms.S-2 ← S	F4 5 3	FC 7 3								
PHX	X ← Ms.S-1 ← S					DA 3 1					
PHY	Y ← Ms.S-1 ← S					5A 3 1					
PHZ	Z ← Ms.S-1 ← S					DB 3 1					
PLA	S ← 1 ← S, Ms ← A					68 3 1					
PLP	S ← 1 ← S, Ms ← P					28 3 1					
PLX	S ← 1 ← S, Ms ← X					FA 3 1					
PLY	S ← 1 ← S, Ms ← Y					7A 3 1					
PLZ	S ← 1 ← S, Ms ← Z					FB 3 1					
RMB	0 ← Mb			(a) 4 2							
ROL	C ← /7...0/ ← C		2E 5 3	26 4 2	2A 1 1						
ROR	C ← /7...0/ ← C		6E 5 3	66 4 2	6A 1 1						
ROW	C ← /15...0/ ← C		EB 6 2								
RTI	ReTurn from Interrupt					40 5 1					
RTN	ReTurn from KerNal					62 7 2					
RTS	ReTurn from Subr					60 4 1					
SBC	A ← M ← 1 ← C ← A	E9 2 2	ED 3 2	E5 3 2			E1 5 2	F1 5 2	F2 5 2		
SEC	1 ← C					38 1 1					
SED	1 ← D					F8 1 1					
SEE	1 ← E					03 2 1					
SEI	1 ← I					78 2 1					
SMB	1 ← Mb			(b) 4 2							
STA	A ← M		8D 4 3	85 3 2			81 5 2	91 5 2	92 5 2	82 6 2	
STX	X ← M		8E 4 3	86 3 2							
STY	Y ← M		8C 4 3	84 3 2							
STZ	Z ← M		9C 4 3	84 3 2							
TAB	A ← B					5B 1 1					
TAX	A ← X					AA 1 1					
TAY	A ← Y					A8 1 1					
TAZ	A ← Z					4B 1 1					
TBA	B ← A					7B 1 1					
TRB	X and M ← M		1C 5 3	14 4 2							
TSB	A or M ← M		0C 5 3	04 4 2							
TSX	S ← X					BA 1 1					
TSY	S ← Y					0B 1 1					
TXA	X ← A					8A 1 1					
TXS	X ← S					9A 1 1					
TYA	Y ← A					9B 1 1					
TYS	Y ← S					2B 1 1					
TZA	Z ← A					6B 1 1					



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## ORDERING INFORMATION

The CSG 65CE02 is available in a plastic 40-pin dual-in-line package with operating frequencies of 2, 4, 6, 8 or 10 MHz. These versions are coded into the part number as follows:

65CE02 -

2 - 2 MHz  
4 - 4 MHz  
6 - 6 MHz  
8 - 8 MHz  
10 - 10 MHz

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